

# Eigenvalues and strong orbit equivalence

María Isabel Cortez

Departamento de Matemática y Ciencia de la Computación  
Universidad de Santiago de Chile.

60 ans JM Gambaudo, Juin, 2018.

- 1 Dimension groups and strong orbit equivalence
- 2 Continuous Eigenvalues
- 3 Relation between eigenvalues and strong orbit equivalence

# General Context

- We deal with **minimal Cantor systems**, i.e, dynamical systems  $(X, T)$  where  $X$  is a Cantor set and  $T : X \rightarrow X$  is a minimal homeomorphism.
- Minimal Cantor systems can be classified in terms of **orbit equivalence** (O.E) classes and **strong orbit equivalence** (S.O.E) classes.
- Some properties of minimal Cantor systems are invariant under O.E and S.O.E. **What about the group of eigenvalues?**
- The algebraic invariants for O.E and S.O.E are essential tools to study this problem.

# General Context

- We deal with **minimal Cantor systems**, i.e, dynamical systems  $(X, T)$  where  $X$  is a Cantor set and  $T : X \rightarrow X$  is a minimal homeomorphism.
- Minimal Cantor systems can be classified in terms of **orbit equivalence** (O.E) classes and **strong orbit equivalence** (S.O.E) classes.
- Some properties of minimal Cantor systems are invariant under O.E and S.O.E. **What about the group of eigenvalues?**
- The algebraic invariants for O.E and S.O.E are essential tools to study this problem.

# General Context

- We deal with **minimal Cantor systems**, i.e, dynamical systems  $(X, T)$  where  $X$  is a Cantor set and  $T : X \rightarrow X$  is a minimal homeomorphism.
- Minimal Cantor systems can be classified in terms of **orbit equivalence** (O.E) classes and **strong orbit equivalence** (S.O.E) classes.
- Some properties of minimal Cantor systems are invariant under O.E and S.O.E. **What about the group of eigenvalues?**
- The algebraic invariants for O.E and S.O.E are essential tools to study this problem.

# General Context

- We deal with **minimal Cantor systems**, i.e, dynamical systems  $(X, T)$  where  $X$  is a Cantor set and  $T : X \rightarrow X$  is a minimal homeomorphism.
- Minimal Cantor systems can be classified in terms of **orbit equivalence** (O.E) classes and **strong orbit equivalence** (S.O.E) classes.
- Some properties of minimal Cantor systems are invariant under O.E and S.O.E. **What about the group of eigenvalues?**
- The algebraic invariants for O.E and S.O.E are essential tools to study this problem.

# Orbit equivalence

- $(X, T)$  and  $(Y, S)$  are **orbit equivalent** if there exists a homeomorphism  $h : X \rightarrow Y$  such that for every  $x \in X$ ,  
$$h(O_T(x)) = O_S(h(x)).$$
- Define  $n, m : X \rightarrow \mathbb{Z}$  as  $h(T(x)) = S^{n(x)}(h(x))$  and  $h(T^{m(x)}(x)) = S(h(x))$ . The systems are **strong orbit equivalent** if  $n$  and  $m$  have at most one point of discontinuity.
- (Boyle)  $n$  and  $m$  are continuous iff the systems are **flip conjugate** ( $T$  is conjugate to  $S$  or  $S^{-1}$ ).
- Conjugacy  $\Rightarrow$  flip conjugacy  $\Rightarrow$  S.O.E  $\Rightarrow$  O.E.

# Orbit equivalence

- $(X, T)$  and  $(Y, S)$  are **orbit equivalent** if there exists a homeomorphism  $h : X \rightarrow Y$  such that for every  $x \in X$ ,  
$$h(O_T(x)) = O_S(h(x)).$$
- Define  $n, m : X \rightarrow \mathbb{Z}$  as  $h(T(x)) = S^{n(x)}(h(x))$  and  $h(T^{m(x)}(x)) = S(h(x))$ . The systems are **strong orbit equivalent** if  $n$  and  $m$  have at most one point of discontinuity.
- (Boyle)  $n$  and  $m$  are continuous iff the systems are **flip conjugate** ( $T$  is conjugate to  $S$  or  $S^{-1}$ ).
- Conjugacy  $\Rightarrow$  flip conjugacy  $\Rightarrow$  S.O.E  $\Rightarrow$  O.E.



# Orbit equivalence

- $(X, T)$  and  $(Y, S)$  are **orbit equivalent** if there exists a homeomorphism  $h : X \rightarrow Y$  such that for every  $x \in X$ ,  
$$h(O_T(x)) = O_S(h(x)).$$
- Define  $n, m : X \rightarrow \mathbb{Z}$  as  $h(T(x)) = S^{n(x)}(h(x))$  and  $h(T^{m(x)}(x)) = S(h(x))$ . The systems are **strong orbit equivalent** if  $n$  and  $m$  have at most one point of discontinuity.
- (Boyle)  $n$  and  $m$  are continuous iff the systems are **flip conjugate** ( $T$  is conjugate to  $S$  or  $S^{-1}$ ).
- Conjugacy  $\Rightarrow$  flip conjugacy  $\Rightarrow$  S.O.E  $\Rightarrow$  O.E.

# Orbit equivalence

- $(X, T)$  and  $(Y, S)$  are **orbit equivalent** if there exists a homeomorphism  $h : X \rightarrow Y$  such that for every  $x \in X$ ,  
$$h(O_T(x)) = O_S(h(x)).$$
- Define  $n, m : X \rightarrow \mathbb{Z}$  as  $h(T(x)) = S^{n(x)}(h(x))$  and  $h(T^{m(x)}(x)) = S(h(x))$ . The systems are **strong orbit equivalent** if  $n$  and  $m$  have at most one point of discontinuity.
- (Boyle)  $n$  and  $m$  are continuous iff the systems are **flip conjugate** ( $T$  is conjugate to  $S$  or  $S^{-1}$ ).
- Conjugacy  $\Rightarrow$  flip conjugacy  $\Rightarrow$  S.O.E  $\Rightarrow$  O.E.

# Algebraic invariants

(Giordano, Putnam, Skau 95, 96)

Property	Algebraic Invariant
Flip conjugacy	topological full group
<b>Strong orbit equivalence</b>	<b>dimension group</b>
Orbit equivalence	reduced dimension group and full group

# Properties which are invariant

- If  $(X, T)$  and  $(Y, S)$  are O.E then there is an affine bijection between their spaces of invariant probability measures.
- Thus systems with different numbers of ergodic measures can not be O.E.
- The converse is not true (there are infinitely many S.O.E classes among the family of uniquely ergodic systems).
- The topological entropy fails: for every  $t \in [0, \infty]$  and for every minimal Cantor system  $(X, T)$ , there exists a minimal Cantor system  $(Y, S)$  which is S.O.E with  $(X, T)$  and such that  $h_{top}(Y, S) = t$ .
- What about the **group of eigenvalues** associated to  $(X, T)$ ?

# Properties which are invariant

- If  $(X, T)$  and  $(Y, S)$  are O.E then there is an affine bijection between their spaces of invariant probability measures.
- Thus systems with different numbers of ergodic measures can not be O.E.
- The converse is not true (there are infinitely many S.O.E classes among the family of uniquely ergodic systems).
- The topological entropy fails: for every  $t \in [0, \infty]$  and for every minimal Cantor system  $(X, T)$ , there exists a minimal Cantor system  $(Y, S)$  which is S.O.E with  $(X, T)$  and such that  $h_{top}(Y, S) = t$ .
- What about the **group of eigenvalues** associated to  $(X, T)$ ?

# Properties which are invariant

- If  $(X, T)$  and  $(Y, S)$  are O.E then there is an affine bijection between their spaces of invariant probability measures.
- Thus systems with different numbers of ergodic measures can not be O.E.
- The converse is not true (there are infinitely many S.O.E classes among the family of uniquely ergodic systems).
- The topological entropy fails: for every  $t \in [0, \infty]$  and for every minimal Cantor system  $(X, T)$ , there exists a minimal Cantor system  $(Y, S)$  which is S.O.E with  $(X, T)$  and such that  $h_{top}(Y, S) = t$ .
- What about the **group of eigenvalues** associated to  $(X, T)$ ?

# Properties which are invariant

- If  $(X, T)$  and  $(Y, S)$  are O.E then there is an affine bijection between their spaces of invariant probability measures.
- Thus systems with different numbers of ergodic measures can not be O.E.
- The converse is not true (there are infinitely many S.O.E classes among the family of uniquely ergodic systems).
- The topological entropy fails: for every  $t \in [0, \infty]$  and for every minimal Cantor system  $(X, T)$ , there exists a minimal Cantor system  $(Y, S)$  which is S.O.E with  $(X, T)$  and such that  $h_{top}(Y, S) = t$ .
- What about the **group of eigenvalues** associated to  $(X, T)$ ?

# Properties which are invariant

- If  $(X, T)$  and  $(Y, S)$  are O.E then there is an affine bijection between their spaces of invariant probability measures.
- Thus systems with different numbers of ergodic measures can not be O.E.
- The converse is not true (there are infinitely many S.O.E classes among the family of uniquely ergodic systems).
- The topological entropy fails: for every  $t \in [0, \infty]$  and for every minimal Cantor system  $(X, T)$ , there exists a minimal Cantor system  $(Y, S)$  which is S.O.E with  $(X, T)$  and such that  $h_{top}(Y, S) = t$ .
- What about the **group of eigenvalues** associated to  $(X, T)$ ?



# Eigenvalues

- Let  $(X, T)$  be a minimal Cantor system.
- An **eigenvalue** of  $(X, T)$  is a number  $\alpha \in \mathbb{R}$  for which there exists  $f \in C(X, \mathbb{C}) \setminus \{0\}$  (called eigenfunction) such that

$$f \circ T = \exp(2i\pi\alpha)f.$$

- If  $T$  is transitive (in particular, minimal) and  $f \in C(X, \mathbb{C})$  is an eigenfunction associated to the eigenvalue  $\alpha$ , then  $|f|$  is constant. Normalizing  $f$  we can assume that  $f : X \rightarrow S^1$ .
- Thus  $f$  is a factor map from  $(X, T)$  to  $(S^1, R_\alpha)$ , where  $R_\alpha$  is the  $\alpha$  rotation on the circle.

# Eigenvalues

- Let  $(X, T)$  be a minimal Cantor system.
- An **eigenvalue** of  $(X, T)$  is a number  $\alpha \in \mathbb{R}$  for which there exists  $f \in C(X, \mathbb{C}) \setminus \{0\}$  (called eigenfunction) such that

$$f \circ T = \exp(2i\pi\alpha)f.$$

- If  $T$  is transitive (in particular, minimal) and  $f \in C(X, \mathbb{C})$  is an eigenfunction associated to the eigenvalue  $\alpha$ , then  $|f|$  is constant. Normalizing  $f$  we can assume that  $f : X \rightarrow S^1$ .
- Thus  $f$  is a factor map from  $(X, T)$  to  $(S^1, R_\alpha)$ , where  $R_\alpha$  is the  $\alpha$  rotation on the circle.

# Eigenvalues

- Let  $(X, T)$  be a minimal Cantor system.
- An **eigenvalue** of  $(X, T)$  is a number  $\alpha \in \mathbb{R}$  for which there exists  $f \in C(X, \mathbb{C}) \setminus \{0\}$  (called eigenfunction) such that

$$f \circ T = \exp(2i\pi\alpha)f.$$

- If  $T$  is transitive (in particular, minimal) and  $f \in C(X, \mathbb{C})$  is an eigenfunction associated to the eigenvalue  $\alpha$ , then  $|f|$  is constant. Normalizing  $f$  we can assume that  $f : X \rightarrow S^1$ .
- Thus  $f$  is a factor map from  $(X, T)$  to  $(S^1, R_\alpha)$ , where  $R_\alpha$  is the  $\alpha$  rotation on the circle.

# Eigenvalues

- Let  $(X, T)$  be a minimal Cantor system.
- An **eigenvalue** of  $(X, T)$  is a number  $\alpha \in \mathbb{R}$  for which there exists  $f \in C(X, \mathbb{C}) \setminus \{0\}$  (called eigenfunction) such that

$$f \circ T = \exp(2i\pi\alpha)f.$$

- If  $T$  is transitive (in particular, minimal) and  $f \in C(X, \mathbb{C})$  is an eigenfunction associated to the eigenvalue  $\alpha$ , then  $|f|$  is constant. Normalizing  $f$  we can assume that  $f : X \rightarrow S^1$ .
- Thus  $f$  is a factor map from  $(X, T)$  to  $(S^1, R_\alpha)$ , where  $R_\alpha$  is the  $\alpha$  rotation on the circle.

# Group of eigenvalues

- We denote  $E(X, T)$  the subset of  $\mathbb{R}$  containing all the eigenvalues of  $(X, T)$ .
- **Remark:**  $E(X, T)$  is a subgroup of  $(\mathbb{R}, +)$ .
- **Remark:**  $\mathbb{Z} \subseteq E(X, T)$  (the constant functions are eigenfunctions associated to the integers).
- $E(X, T)$  contains the information about the rotations on the circle which are semi conjugate to  $(X, T)$ .

# Group of eigenvalues

- We denote  $E(X, T)$  the subset of  $\mathbb{R}$  containing all the eigenvalues of  $(X, T)$ .
- **Remark:**  $E(X, T)$  is a subgroup of  $(\mathbb{R}, +)$ .
- **Remark:**  $\mathbb{Z} \subseteq E(X, T)$  (the constant functions are eigenfunctions associated to the integers).
- $E(X, T)$  contains the information about the rotations on the circle which are semi conjugate to  $(X, T)$ .

# Group of eigenvalues

- We denote  $E(X, T)$  the subset of  $\mathbb{R}$  containing all the eigenvalues of  $(X, T)$ .
- **Remark:**  $E(X, T)$  is a subgroup of  $(\mathbb{R}, +)$ .
- **Remark:**  $\mathbb{Z} \subseteq E(X, T)$  (the constant functions are eigenfunctions associated to the integers).
- $E(X, T)$  contains the information about the rotations on the circle which are semi conjugate to  $(X, T)$ .

## Group of eigenvalues

- We denote  $E(X, T)$  the subset of  $\mathbb{R}$  containing all the eigenvalues of  $(X, T)$ .
- **Remark:**  $E(X, T)$  is a subgroup of  $(\mathbb{R}, +)$ .
- **Remark:**  $\mathbb{Z} \subseteq E(X, T)$  (the constant functions are eigenfunctions associated to the integers).
- $E(X, T)$  contains the information about the rotations on the circle which are semi conjugate to  $(X, T)$ .



# Dimension group

- Let  $(X, T)$  be a minimal Cantor system.
- Consider the additive group  $C(X, \mathbb{Z})$  (this is abelian and countable).
- Consider the subgroup
$$\partial_T C(X, \mathbb{Z}) = \{f - f \circ T : f \in C(X, \mathbb{Z})\}.$$
- We define  $D(X, T) = C(X, \mathbb{Z})/\partial_T C(X, \mathbb{Z})$  and  $D^+(X, T) = \{[f] : f \geq 0\}$ .
- The pair  $(D(X, T), D^+(X, T))$  is an ordered group.
- The **dimension group with unit** associated to  $(X, T)$  is  $K^0(X, T) = (D(X, T), D^+(X, T), [1_X])$ .

# Dimension group

- Let  $(X, T)$  be a minimal Cantor system.
- Consider the additive group  $C(X, \mathbb{Z})$  (this is abelian and countable).
- Consider the subgroup
$$\partial_T C(X, \mathbb{Z}) = \{f - f \circ T : f \in C(X, \mathbb{Z})\}.$$
- We define  $D(X, T) = C(X, \mathbb{Z})/\partial_T C(X, \mathbb{Z})$  and  $D^+(X, T) = \{[f] : f \geq 0\}$ .
- The pair  $(D(X, T), D^+(X, T))$  is an ordered group.
- The **dimension group with unit** associated to  $(X, T)$  is  $K^0(X, T) = (D(X, T), D^+(X, T), [1_X])$ .

# Dimension group

- Let  $(X, T)$  be a minimal Cantor system.
- Consider the additive group  $C(X, \mathbb{Z})$  (this is abelian and countable).
- Consider the subgroup
$$\partial_T C(X, \mathbb{Z}) = \{f - f \circ T : f \in C(X, \mathbb{Z})\}.$$
- We define  $D(X, T) = C(X, \mathbb{Z})/\partial_T C(X, \mathbb{Z})$  and  $D^+(X, T) = \{[f] : f \geq 0\}$ .
- The pair  $(D(X, T), D^+(X, T))$  is an ordered group.
- The **dimension group with unit** associated to  $(X, T)$  is  $K^0(X, T) = (D(X, T), D^+(X, T), [1_X])$ .

# Dimension group

- Let  $(X, T)$  be a minimal Cantor system.
- Consider the additive group  $C(X, \mathbb{Z})$  (this is abelian and countable).
- Consider the subgroup
$$\partial_T C(X, \mathbb{Z}) = \{f - f \circ T : f \in C(X, \mathbb{Z})\}.$$
- We define  $D(X, T) = C(X, \mathbb{Z}) / \partial_T C(X, \mathbb{Z})$  and  $D^+(X, T) = \{[f] : f \geq 0\}$ .
- The pair  $(D(X, T), D^+(X, T))$  is an ordered group.
- The **dimension group with unit** associated to  $(X, T)$  is  $K^0(X, T) = (D(X, T), D^+(X, T), [1_X])$ .

# Dimension group

- Let  $(X, T)$  be a minimal Cantor system.
- Consider the additive group  $C(X, \mathbb{Z})$  (this is abelian and countable).
- Consider the subgroup
$$\partial_T C(X, \mathbb{Z}) = \{f - f \circ T : f \in C(X, \mathbb{Z})\}.$$
- We define  $D(X, T) = C(X, \mathbb{Z}) / \partial_T C(X, \mathbb{Z})$  and  $D^+(X, T) = \{[f] : f \geq 0\}$ .
- The pair  $(D(X, T), D^+(X, T))$  is an ordered group.
- The **dimension group with unit** associated to  $(X, T)$  is  $K^0(X, T) = (D(X, T), D^+(X, T), [1_X])$ .

# Dimension group

- Let  $(X, T)$  be a minimal Cantor system.
- Consider the additive group  $C(X, \mathbb{Z})$  (this is abelian and countable).
- Consider the subgroup
$$\partial_T C(X, \mathbb{Z}) = \{f - f \circ T : f \in C(X, \mathbb{Z})\}.$$
- We define  $D(X, T) = C(X, \mathbb{Z}) / \partial_T C(X, \mathbb{Z})$  and  $D^+(X, T) = \{[f] : f \geq 0\}$ .
- The pair  $(D(X, T), D^+(X, T))$  is an ordered group.
- The **dimension group with unit** associated to  $(X, T)$  is  $K^0(X, T) = (D(X, T), D^+(X, T), [1_X])$ .

# Invariant for strong orbit equivalence.

## Theorem

*(Giordano, Putnam, Skau 95)  $(X, T)$  and  $(Y, S)$  are S.O.E if and only if  $K^0(X, T)$  and  $K^0(Y, S)$  are isomorphic as dimension groups with unit.*

# States or traces

- A **state** or **trace** of  $K^0(X, T)$  is a homomorphism  $\tau : D(X, T) \rightarrow \mathbb{R}$  such that  $\tau(D^+(X, T)) \subseteq \mathbb{R}^+$  and  $\tau([1_X]) = 1$ .
- It is not difficult to show that the following function is an affine bijection between  $\mathcal{M}(X, T)$  and the set of traces:

$$\mu \longrightarrow \tau_\mu \text{ where } \tau_\mu([f]) = \int f d\mu.$$

- (Many ways to show this):

$$E(X, T) \subseteq I(X, T) = \bigcap_{\tau \text{ trace}} \tau(D(X, T)).$$



# States or traces

- A **state** or **trace** of  $K^0(X, T)$  is a homomorphism  $\tau : D(X, T) \rightarrow \mathbb{R}$  such that  $\tau(D^+(X, T)) \subseteq \mathbb{R}^+$  and  $\tau([1_X]) = 1$ .
- It is not difficult to show that the following function is an affine bijection between  $\mathcal{M}(X, T)$  and the set of traces:

$$\mu \longrightarrow \tau_\mu \text{ where } \tau_\mu([f]) = \int f d\mu.$$

- (Many ways to show this):

$$E(X, T) \subseteq I(X, T) = \bigcap_{\tau \text{ trace}} \tau(D(X, T)).$$

# States or traces

- A **state** or **trace** of  $K^0(X, T)$  is a homomorphism  $\tau : D(X, T) \rightarrow \mathbb{R}$  such that  $\tau(D^+(X, T)) \subseteq \mathbb{R}^+$  and  $\tau([1_X]) = 1$ .
- It is not difficult to show that the following function is an affine bijection between  $\mathcal{M}(X, T)$  and the set of traces:

$$\mu \longrightarrow \tau_\mu \text{ where } \tau_\mu([f]) = \int f d\mu.$$

- (Many ways to show this):

$$E(X, T) \subseteq I(X, T) = \bigcap_{\tau \text{ trace}} \tau(D(X, T)).$$

# Example

- Let  $\alpha \in [0, 1] \setminus \mathbb{Q}$  and  $(X_\alpha, T_\alpha)$  be the associated Sturmian subshift.
- $K^0(X_\alpha, T_\alpha)$  is isomorphic to  $(\mathbb{Z} + \alpha\mathbb{Z}, (\mathbb{Z} + \alpha\mathbb{Z}) \cap \mathbb{R}^+, 1)$ .
- The only trace for this dimension group is the identity. Then  $I(X_\alpha, T_\alpha) = \mathbb{Z} + \alpha\mathbb{Z}$ .
- On the other hand, we know that  $\alpha \in E(X_\alpha, T_\alpha)$ , then  $\mathbb{Z} + \alpha\mathbb{Z} \subseteq E(X_\alpha, T_\alpha)$
- We deduce  $\mathbb{Z} + \alpha\mathbb{Z} = E(X_\alpha, T_\alpha) = I(X_\alpha, T_\alpha)$ .
- If  $(X, T)$  is S.O.E with  $(X_\alpha, T_\alpha)$  then  $E(X, T)$  is a subgroup of  $\mathbb{Z} + \alpha\mathbb{Z}$ . What kind of subgroups of  $\mathbb{Z} + \alpha\mathbb{Z}$  we can realize as  $E(X, T)$ ?

# Example

- Let  $\alpha \in [0, 1] \setminus \mathbb{Q}$  and  $(X_\alpha, T_\alpha)$  be the associated Sturmian subshift.
- $K^0(X_\alpha, T_\alpha)$  is isomorphic to  $(\mathbb{Z} + \alpha\mathbb{Z}, (\mathbb{Z} + \alpha\mathbb{Z}) \cap \mathbb{R}^+, 1)$ .
- The only trace for this dimension group is the identity. Then  $I(X_\alpha, T_\alpha) = \mathbb{Z} + \alpha\mathbb{Z}$ .
- On the other hand, we know that  $\alpha \in E(X_\alpha, T_\alpha)$ , then  $\mathbb{Z} + \alpha\mathbb{Z} \subseteq E(X_\alpha, T_\alpha)$
- We deduce  $\mathbb{Z} + \alpha\mathbb{Z} = E(X_\alpha, T_\alpha) = I(X_\alpha, T_\alpha)$ .
- If  $(X, T)$  is S.O.E with  $(X_\alpha, T_\alpha)$  then  $E(X, T)$  is a subgroup of  $\mathbb{Z} + \alpha\mathbb{Z}$ . What kind of subgroups of  $\mathbb{Z} + \alpha\mathbb{Z}$  we can realize as  $E(X, T)$ ?

## Example

- Let  $\alpha \in [0, 1] \setminus \mathbb{Q}$  and  $(X_\alpha, T_\alpha)$  be the associated Sturmian subshift.
- $K^0(X_\alpha, T_\alpha)$  is isomorphic to  $(\mathbb{Z} + \alpha\mathbb{Z}, (\mathbb{Z} + \alpha\mathbb{Z}) \cap \mathbb{R}^+, 1)$ .
- The only trace for this dimension group is the identity. Then  $I(X_\alpha, T_\alpha) = \mathbb{Z} + \alpha\mathbb{Z}$ .
- On the other hand, we know that  $\alpha \in E(X_\alpha, T_\alpha)$ , then  $\mathbb{Z} + \alpha\mathbb{Z} \subseteq E(X_\alpha, T_\alpha)$
- We deduce  $\mathbb{Z} + \alpha\mathbb{Z} = E(X_\alpha, T_\alpha) = I(X_\alpha, T_\alpha)$ .
- If  $(X, T)$  is S.O.E with  $(X_\alpha, T_\alpha)$  then  $E(X, T)$  is a subgroup of  $\mathbb{Z} + \alpha\mathbb{Z}$ . What kind of subgroups of  $\mathbb{Z} + \alpha\mathbb{Z}$  we can realize as  $E(X, T)$ ?

# Example

- Let  $\alpha \in [0, 1] \setminus \mathbb{Q}$  and  $(X_\alpha, T_\alpha)$  be the associated Sturmian subshift.
- $K^0(X_\alpha, T_\alpha)$  is isomorphic to  $(\mathbb{Z} + \alpha\mathbb{Z}, (\mathbb{Z} + \alpha\mathbb{Z}) \cap \mathbb{R}^+, 1)$ .
- The only trace for this dimension group is the identity. Then  $I(X_\alpha, T_\alpha) = \mathbb{Z} + \alpha\mathbb{Z}$ .
- On the other hand, we know that  $\alpha \in E(X_\alpha, T_\alpha)$ , then  $\mathbb{Z} + \alpha\mathbb{Z} \subseteq E(X_\alpha, T_\alpha)$
- We deduce  $\mathbb{Z} + \alpha\mathbb{Z} = E(X_\alpha, T_\alpha) = I(X_\alpha, T_\alpha)$ .
- If  $(X, T)$  is S.O.E with  $(X_\alpha, T_\alpha)$  then  $E(X, T)$  is a subgroup of  $\mathbb{Z} + \alpha\mathbb{Z}$ . What kind of subgroups of  $\mathbb{Z} + \alpha\mathbb{Z}$  we can realize as  $E(X, T)$ ?

## Example

- Let  $\alpha \in [0, 1] \setminus \mathbb{Q}$  and  $(X_\alpha, T_\alpha)$  be the associated Sturmian subshift.
- $K^0(X_\alpha, T_\alpha)$  is isomorphic to  $(\mathbb{Z} + \alpha\mathbb{Z}, (\mathbb{Z} + \alpha\mathbb{Z}) \cap \mathbb{R}^+, 1)$ .
- The only trace for this dimension group is the identity. Then  $I(X_\alpha, T_\alpha) = \mathbb{Z} + \alpha\mathbb{Z}$ .
- On the other hand, we know that  $\alpha \in E(X_\alpha, T_\alpha)$ , then  $\mathbb{Z} + \alpha\mathbb{Z} \subseteq E(X_\alpha, T_\alpha)$
- We deduce  $\mathbb{Z} + \alpha\mathbb{Z} = E(X_\alpha, T_\alpha) = I(X_\alpha, T_\alpha)$ .
- If  $(X, T)$  is S.O.E with  $(X_\alpha, T_\alpha)$  then  $E(X, T)$  is a subgroup of  $\mathbb{Z} + \alpha\mathbb{Z}$ . What kind of subgroups of  $\mathbb{Z} + \alpha\mathbb{Z}$  we can realize as  $E(X, T)$ ?

# Example

- Let  $\alpha \in [0, 1] \setminus \mathbb{Q}$  and  $(X_\alpha, T_\alpha)$  be the associated Sturmian subshift.
- $K^0(X_\alpha, T_\alpha)$  is isomorphic to  $(\mathbb{Z} + \alpha\mathbb{Z}, (\mathbb{Z} + \alpha\mathbb{Z}) \cap \mathbb{R}^+, 1)$ .
- The only trace for this dimension group is the identity. Then  $I(X_\alpha, T_\alpha) = \mathbb{Z} + \alpha\mathbb{Z}$ .
- On the other hand, we know that  $\alpha \in E(X_\alpha, T_\alpha)$ , then  $\mathbb{Z} + \alpha\mathbb{Z} \subseteq E(X_\alpha, T_\alpha)$
- We deduce  $\mathbb{Z} + \alpha\mathbb{Z} = E(X_\alpha, T_\alpha) = I(X_\alpha, T_\alpha)$ .
- If  $(X, T)$  is S.O.E with  $(X_\alpha, T_\alpha)$  then  $E(X, T)$  is a subgroup of  $\mathbb{Z} + \alpha\mathbb{Z}$ . What kind of subgroups of  $\mathbb{Z} + \alpha\mathbb{Z}$  we can realize as  $E(X, T)$ ?



# Rational subgroup

- The **rational group** associated to  $K^0(X, T)$  is defined as

$$Q(K^0(X, T)) = \langle \left\{ \frac{1}{n} : n \in \mathbb{N} \text{ s.t. } \exists [f] \in D(X, T) \text{ s.t. } n[f] = [1_X] \right\} \rangle.$$

- $\mathbb{Z} \leq Q(K^0(X, T)) \leq \mathbb{Q}$ .
- The rational subgroup is invariant under S.O.E.
- In the case of the S.O.E class of the Sturmian subshift we have  $Q(K^0(X_\alpha, T_\alpha)) = \mathbb{Z}$ .

# Rational subgroup

- The **rational group** associated to  $K^0(X, T)$  is defined as

$$Q(K^0(X, T)) = \langle \left\{ \frac{1}{n} : n \in \mathbb{N} \text{ s.t. } \exists [f] \in D(X, T) \text{ s.t. } n[f] = [1_X] \right\} \rangle.$$

- $\mathbb{Z} \leq Q(K^0(X, T)) \leq \mathbb{Q}$ .
- The rational subgroup is invariant under S.O.E.
- In the case of the S.O.E class of the Sturmian subshift we have  $Q(K^0(X_\alpha, T_\alpha)) = \mathbb{Z}$ .

# Rational subgroup

- The **rational group** associated to  $K^0(X, T)$  is defined as

$$Q(K^0(X, T)) = \langle \left\{ \frac{1}{n} : n \in \mathbb{N} \text{ s.t. } \exists [f] \in D(X, T) \text{ s.t. } n[f] = [1_X] \right\} \rangle.$$

- $\mathbb{Z} \leq Q(K^0(X, T)) \leq \mathbb{Q}$ .
- The rational subgroup is invariant under S.O.E.
- In the case of the S.O.E class of the Sturmian subshift we have  $Q(K^0(X_\alpha, T_\alpha)) = \mathbb{Z}$ .

# Rational subgroup

- The **rational group** associated to  $K^0(X, T)$  is defined as

$$Q(K^0(X, T)) = \langle \left\{ \frac{1}{n} : n \in \mathbb{N} \text{ s.t. } \exists [f] \in D(X, T) \text{ s.t. } n[f] = [1_X] \right\} \rangle.$$

- $\mathbb{Z} \leq Q(K^0(X, T)) \leq \mathbb{Q}$ .
- The rational subgroup is invariant under S.O.E.
- In the case of the S.O.E class of the Sturmian subshift we have  $Q(K^0(X_\alpha, T_\alpha)) = \mathbb{Z}$ .

# Rational eigenvalues and rational subgroup

Ormes 97:

- $E(X, T) \cap \mathbb{Q} = Q(K^0(X, T))$ .
- Thus the rational eigenvalues are invariant under S.O.E.
- If  $Q(K^0(X, T)) = \mathbb{Z}$  then there exists  $(Y, S)$  S.O.E with  $(X, T)$  such that  $E(X, T) = \mathbb{Z}$ .
- Example: there exists  $(Y, S)$  S.O.E with  $(X_\alpha, T_\alpha)$  such that  $E(Y, S) = \mathbb{Z}$ .
- Conclusion: the group of eigenvalues **is not invariant** under S.O.E...but there are still some restrictions.

# Rational eigenvalues and rational subgroup

Ormes 97:

- $E(X, T) \cap \mathbb{Q} = Q(K^0(X, T))$ .
- Thus the rational eigenvalues are invariant under S.O.E.
- If  $Q(K^0(X, T)) = \mathbb{Z}$  then there exists  $(Y, S)$  S.O.E with  $(X, T)$  such that  $E(X, T) = \mathbb{Z}$ .
- Example: there exists  $(Y, S)$  S.O.E with  $(X_\alpha, T_\alpha)$  such that  $E(Y, S) = \mathbb{Z}$ .
- Conclusion: the group of eigenvalues **is not invariant** under S.O.E...but there are still some restrictions.

# Rational eigenvalues and rational subgroup

Ormes 97:

- $E(X, T) \cap \mathbb{Q} = Q(K^0(X, T))$ .
- Thus the rational eigenvalues are invariant under S.O.E.
- If  $Q(K^0(X, T)) = \mathbb{Z}$  then there exists  $(Y, S)$  S.O.E with  $(X, T)$  such that  $E(X, T) = \mathbb{Z}$ .
- Example: there exists  $(Y, S)$  S.O.E with  $(X_\alpha, T_\alpha)$  such that  $E(Y, S) = \mathbb{Z}$ .
- Conclusion: the group of eigenvalues is **not invariant** under S.O.E...but there are still some restrictions.

# Rational eigenvalues and rational subgroup

Ormes 97:

- $E(X, T) \cap \mathbb{Q} = Q(K^0(X, T))$ .
- Thus the rational eigenvalues are invariant under S.O.E.
- If  $Q(K^0(X, T)) = \mathbb{Z}$  then there exists  $(Y, S)$  S.O.E with  $(X, T)$  such that  $E(X, T) = \mathbb{Z}$ .
- Example: there exists  $(Y, S)$  S.O.E with  $(X_\alpha, T_\alpha)$  such that  $E(Y, S) = \mathbb{Z}$ .
- Conclusion: the group of eigenvalues is **not invariant** under S.O.E...but there are still some restrictions.



# Rational eigenvalues and rational subgroup

Ormes 97:

- $E(X, T) \cap \mathbb{Q} = Q(K^0(X, T))$ .
- Thus the rational eigenvalues are invariant under S.O.E.
- If  $Q(K^0(X, T)) = \mathbb{Z}$  then there exists  $(Y, S)$  S.O.E with  $(X, T)$  such that  $E(X, T) = \mathbb{Z}$ .
- Example: there exists  $(Y, S)$  S.O.E with  $(X_\alpha, T_\alpha)$  such that  $E(Y, S) = \mathbb{Z}$ .
- Conclusion: the group of eigenvalues **is not invariant** under S.O.E...but there are still some restrictions.

# Infinitesimal subgroup

- The **infinitesimal subgroup** of  $K^0(X, T)$  is

$$\text{inf}(K^0(X, T)) = \bigcap_{\tau \text{ trace}} \text{Ker}(\tau).$$

- If  $(X, T)$  is uniquely ergodic then  $K^0(X, T)/\text{inf}(K^0(X, T))$  is isomorphic to  $(I(X, T), I(X, T) \cap \mathbb{R}^+, 1)$ .
- And If in addition, the infinitesimal subgroup is trivial (as for the Sturmian subshift), then  $K^0(X, T)$  is isomorphic to  $(I(X, T), I(X, T) \cap \mathbb{R}^+, 1)$ .

# Infinitesimal subgroup

- The **infinitesimal subgroup** of  $K^0(X, T)$  is

$$\text{inf}(K^0(X, T)) = \bigcap_{\tau \text{ trace}} \text{Ker}(\tau).$$

- If  $(X, T)$  is uniquely ergodic then  $K^0(X, T)/\text{inf}(K^0(X, T))$  is isomorphic to  $(I(X, T), I(X, T) \cap \mathbb{R}^+, 1)$ .
- And If in addition, the infinitesimal subgroup is trivial (as for the Sturmian subshift), then  $K^0(X, T)$  is isomorphic to  $(I(X, T), I(X, T) \cap \mathbb{R}^+, 1)$ .

# Infinitesimal subgroup

- The **infinitesimal subgroup** of  $K^0(X, T)$  is

$$\text{inf}(K^0(X, T)) = \bigcap_{\tau \text{ trace}} \text{Ker}(\tau).$$

- If  $(X, T)$  is uniquely ergodic then  $K^0(X, T)/\text{inf}(K^0(X, T))$  is isomorphic to  $(I(X, T), I(X, T) \cap \mathbb{R}^+, 1)$ .
- And If in addition, the infinitesimal subgroup is trivial (as for the Sturmian subshift), then  $K^0(X, T)$  is isomorphic to  $(I(X, T), I(X, T) \cap \mathbb{R}^+, 1)$ .

# Eigenvalues and dimension groups.

## Theorem

(C., Durand, Petite, 2016) Let  $(X, T)$  be a minimal Cantor system such that the infinitesimal subgroup of  $K^0(X, T)$  is trivial. Then  $I(X, T)/E(X, T)$  is torsion free or trivial. This is not always true if the infinitesimal subgroup is not trivial.

## Example and questions

- If  $K^0(X, T)$  is isomorphic to  $K^0(X_\alpha, T_\alpha)$  then  $E(X, T) \in \{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}\}$ .
- We know that each group in  $\{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}\}$  is realized as the group of eigenvalues of a system in the S.O.E class of the Sturmian subshift.
- What about the groups of eigenvalues that can be realized in any other S.O.E class?
- Suppose that  $\alpha$  and  $\beta$  are rationally independent. If  $K^0(X, T)$  is isomorphic to  $\mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}$ , then  $E(X, T)$  is in  $\{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}, \mathbb{Z} + \beta\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}\}$ .
- In the previous case, it is possible to realize  $\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}$  and  $\mathbb{Z} + \beta\mathbb{Z}$  as  $E(X, T)$ . What about  $\mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}$ ?

## Example and questions

- If  $K^0(X, T)$  is isomorphic to  $K^0(X_\alpha, T_\alpha)$  then  $E(X, T) \in \{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}\}$ .
- We know that each group in  $\{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}\}$  is realized as the group of eigenvalues of a system in the S.O.E class of the Sturmian subshift.
- What about the groups of eigenvalues that can be realized in any other S.O.E class?
- Suppose that  $\alpha$  and  $\beta$  are rationally independent. If  $K^0(X, T)$  is isomorphic to  $\mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}$ , then  $E(X, T)$  is in  $\{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}, \mathbb{Z} + \beta\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}\}$ .
- In the previous case, it is possible to realize  $\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}$  and  $\mathbb{Z} + \beta\mathbb{Z}$  as  $E(X, T)$ . What about  $\mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}$ ?

## Example and questions

- If  $K^0(X, T)$  is isomorphic to  $K^0(X_\alpha, T_\alpha)$  then  $E(X, T) \in \{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}\}$ .
- We know that each group in  $\{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}\}$  is realized as the group of eigenvalues of a system in the S.O.E class of the Sturmian subshift.
- What about the groups of eigenvalues that can be realized in any other S.O.E class?
- Suppose that  $\alpha$  and  $\beta$  are rationally independent. If  $K^0(X, T)$  is isomorphic to  $\mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}$ , then  $E(X, T)$  is in  $\{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}, \mathbb{Z} + \beta\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}\}$ .
- In the previous case, it is possible to realize  $\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}$  and  $\mathbb{Z} + \beta\mathbb{Z}$  as  $E(X, T)$ . What about  $\mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}$ ?



## Example and questions

- If  $K^0(X, T)$  is isomorphic to  $K^0(X_\alpha, T_\alpha)$  then  $E(X, T) \in \{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}\}$ .
- We know that each group in  $\{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}\}$  is realized as the group of eigenvalues of a system in the S.O.E class of the Sturmian subshift.
- What about the groups of eigenvalues that can be realized in any other S.O.E class?
- Suppose that  $\alpha$  and  $\beta$  are rationally independent. If  $K^0(X, T)$  is isomorphic to  $\mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}$ , then  $E(X, T)$  is in  $\{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}, \mathbb{Z} + \beta\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}\}$ .
- In the previous case, it is possible to realize  $\mathbb{Z}$ ,  $\mathbb{Z} + \alpha\mathbb{Z}$  and  $\mathbb{Z} + \beta\mathbb{Z}$  as  $E(X, T)$ . What about  $\mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}$ ?

## Example and questions

- If  $K^0(X, T)$  is isomorphic to  $K^0(X_\alpha, T_\alpha)$  then  $E(X, T) \in \{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}\}$ .
- We know that each group in  $\{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}\}$  is realized as the group of eigenvalues of a system in the S.O.E class of the Sturmian subshift.
- What about the groups of eigenvalues that can be realized in any other S.O.E class?
- Suppose that  $\alpha$  and  $\beta$  are rationally independent. If  $K^0(X, T)$  is isomorphic to  $\mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}$ , then  $E(X, T)$  is in  $\{\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z}, \mathbb{Z} + \beta\mathbb{Z}, \mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}\}$ .
- In the previous case, it is possible to realize  $\mathbb{Z}$ ,  $\mathbb{Z} + \alpha\mathbb{Z}$  and  $\mathbb{Z} + \beta\mathbb{Z}$  as  $E(X, T)$ . What about  $\mathbb{Z} + \alpha\mathbb{Z} + \beta\mathbb{Z}$ ?

# Giordano, Handelman, Hosseini (2016)

There exists a monomorphism  $\theta : E(X, T) \rightarrow K^0(X, T)$

## Theorem

(Giordano, Handelman, Hosseini, 2016)  $K^0(X, T)/\theta(E(X, T))$  is torsion free.

- The dimension group is rationally miscible if  $I(X, T) \subseteq \mathbb{Q}$ .
- (GHH) There are rationally miscible dimension groups such that every minimal Cantor system in the respective S.O.E class has no non trivial eigenvalues. These examples are different from the "Sturmian type".

## Giordano, Handelman, Hosseini (2016)

There exists a monomorphism  $\theta : E(X, T) \rightarrow K^0(X, T)$

## Theorem

(Giordano, Handelman, Hosseini, 2016)  $K^0(X, T)/\theta(E(X, T))$  is torsion free.

- The dimension group is irrationally miscible if  $I(X, T) \subseteq \mathbb{Q}$ .
- (GHH) There are irrationally miscible dimension groups such that every minimal Cantor system in the respective S.O.E class has no non trivial eigenvalues. These examples are different from the "Sturmian type".

## Giordano, Handelman, Hosseini (2016)

There exists a monomorphism  $\theta : E(X, T) \rightarrow K^0(X, T)$

## Theorem

(Giordano, Handelman, Hosseini, 2016)  $K^0(X, T)/\theta(E(X, T))$  is torsion free.

- The dimension group is irrationally miscible if  $I(X, T) \subseteq \mathbb{Q}$ .
- (GHH) There are irrationally miscible dimension groups such that every minimal Cantor system in the respective S.O.E class has no non trivial eigenvalues. These examples are different from the "Sturmian type".

Feliz Cumple!!!